

User interface:

1. Graphic display
2. Capacitive keys
3. Mechanical push button




Connector panel:

4. NOT USED
5. Wet sensor
6. NOT USED
7. NOT USED
8. USB
9. Sensor head
10. Robot azimuth and zenith motion
11. DCP / Serial communication
12. Solar panel
13. External battery

Other:

14. GPS antenna
15. GSM antenna
16. NOT USED

IMPORTANT: GPS must be Synchronized first before setting up instrument

1. Connect everything to control box before connecting power
2. Connect power to control box
3. From main menu (*image 1*) scroll down to “CIMEL” and touch  (Enter) button (*image 2*)
4. Scroll down until you see “GPS INFO” and touch the  (Enter) button (*image 3*)
5. Wait up to 15 min for automatic GPS synchronization. When done the coordinates will be displayed on the screen (*image 4*) *******NOTE: “State” will show: Init... => wait GPS... => off**
6. Touch the  (Return) button 4 times to return to the main screen

